

A MARKOV PROPERTY FOR TWO PARAMETER GAUSSIAN PROCESSES (*)

by

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This paper deals with the relationship between two-dimensional parameter Gaussian random fields verifying a particular Markov property and the solutions of stochastic differential equations. In the non Gaussian case some diffusion conditions are introduced, obtaining a backward equation for the evolution of transition probability functions.

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First we examine the Gaussian case and we establish a characterization of random Markov fields by means of two-parameter Wiener processes.

Let $X = \{X(z)\}_{z \in \mathbb{R}^2}$ be a random field, defined on a probability space (Ω, \mathcal{A}, P) . If the random field is only defined on a subset $T \subset \mathbb{R}^2$ we will extend it by putting $X(z) = 0$ if $z \notin T$.

We consider two increasing families of σ -fields:

$$F_z = \sigma \langle X(z'), z' \leq z \rangle ,$$

$$F_z = \sigma \langle X(z'), x' \leq x \text{ or } y' \leq y \rangle , z = (x, y), z' = (x', y') ,$$

which have been defined using the partial ordering of \mathbb{R}^2 :

$$(x_1, y_1) \leq (x_2, y_2) \Leftrightarrow x_1 \leq x_2 \text{ and } y_1 \leq y_2 .$$

(*)

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Given a point $z \in \mathbb{R}^2$, the complementary regions $\{z' \in \mathbb{R}^2 \mid z \leq z'\}$ and $\{z' \in \mathbb{R}^2 \mid x' < x \text{ or } y' < y\}$ represent respectively the "future" and "past" of z .

Definition 1.1.— The random function X is called a two-parameter Markov random field iff

$$P[X(z')/G_z] = P[X(z')/X(x, y'), X(z), X(x', y)],$$

for all $z \leq z'$.

Notice that the two-parameter Wiener process $W = \{W(z)\}_{z \in \mathbb{R}_+^2}$ and any random field on \mathbb{R}_+^2 with independent increments, zero mean and vanishing on the axes satisfy this property.

Let $F_{st}^1 = \bigvee_{y \geq 0} F_{sy}$ and $F_{st}^2 = \bigvee_{x \geq 0} F_{xt}$ for all $(s, t) \in \mathbb{R}_+^2$. We will assume that the family of σ -fields $\{F_z\}_{z \in \mathbb{R}_+^2}$ associated to a random field $X = \{X(z)\}_{z \in \mathbb{R}_+^2}$ satisfies the following conditions:

(1.1) F_{st}^1 and F_{st}^2 are conditionally independent given F_z .

(1.2) $\bigwedge_{s \in \mathbb{R}_+} F_{st}^1$ and $\bigwedge_{t \in \mathbb{R}_+} F_{st}^2$ are trivial σ -fields.

It can be shown (see [3] for the Gaussian case) that Markov property implies (1.1), and (1.2) is true if, for example, the process vanishes in a region $Q_{z_0} = \{(x, y) \mid x \leq x_0 \text{ or } y \leq y_0\}$ for some $z_0 \in \mathbb{R}^2$.

We suppose in this section that X is a Gaussian, zero mean random field and we will denote by $\Gamma(z, z')$ its covariance function. Let $\Gamma(z)$ be the variance of $X(z)$ and let R_z be the rectangle $(-\infty, x] \times (-\infty, y]$ for all $z = (x, y) \in \mathbb{R}^2$.

We first give a characterization of Gaussian martingales.

Proposition 1.1.— The following conditions are equivalent:

- (i) $\{X(z), F_z\}_{z \in \mathbb{R}_+^2}$ is a martingale,
- (ii) X has independent increments,
- (iii) $\Gamma(z, z') = \Gamma(z \wedge z')$, where $z \wedge z' = (x \wedge x', y \wedge y')$.

If $\Gamma(z)$ is absolutely continuous with respect to the Lebesgue measure on \mathbb{R}^2 then the previous conditions are also equivalent to:

(iv) there exists a Brownian measure W on \mathbb{R}^2 and a function $\phi \in L^2(\mathbb{R}^2)$ such that

$$(1.3) \quad X(z) = \int_{\mathbb{R}^2} \phi(\zeta) dW_\zeta.$$

Proof: We will only demonstrate the three first conditions imply the fourth one, because other implications are obvious.

If $\Gamma(z) = \int_{\mathbb{R}^2} \varphi(\zeta) d\zeta$, property (iii) implies the increment of Γ in any rectangle Δ is nonnegative, that is, $\Gamma(\Delta) = E[X(\Delta)]^2 \geq 0$, therefore we can suppose $\varphi(\zeta) \geq 0$ for all $\zeta \in \mathbb{R}^2$. and take $\phi(\zeta) = \sqrt{\varphi(\zeta)}$.

Let us consider two cases:

(a) If $\phi(\zeta) \neq 0$ for all $\zeta \in \mathbb{R}^2$, then $W(A) = \int_A \frac{1}{\phi(\zeta)} dX(\zeta)$, where A is a bounded measurable subset of \mathbb{R}^2 , defines a Brownian measure on \mathbb{R}^2 which satisfies (1.3).

(b) If ϕ vanishes in some point ζ , we take $\frac{1}{\phi(\zeta)} = 0$.

Let W_0 be a Brownian measure on \mathbb{R}^2 independent of X (it can always be constructed modifying the probability space (Ω, \mathcal{A}, P)) and D the set $\{\zeta \in \mathbb{R}^2 / \phi(\zeta) = 0\}$. Then property (iv) follows from

$$W(A) = \int_A \frac{1}{\phi(\zeta)} dX(\zeta) + W_0(D \cap A). \quad \square$$

Notice that property (iv) imply conditions (1.1) and (1.2).

Let $\phi(z, z')$ a real function defined by

$$\begin{aligned} \phi(z, z') &= \Gamma(z, z') \Gamma(z', z')^{-1} && \text{if } z' \leq z, z' \neq z \text{ and } \Gamma(z', z') \neq 0, \\ \phi(z, z') &= 0 && \text{if } z' \leq z, z' \neq z \text{ and } \Gamma(z', z') = 0, \\ \phi(z, z) &= 1. \end{aligned}$$

ϕ represents a transmission function, as in the one dimensional parameter processes, and satisfies

$$E[X(z)/X(z')] = \phi(z, z') \cdot X(z'), \text{ if } z' \leq z.$$

Proposition 1.2.- The process $X = \{X(z)\}_{z \in \mathbb{R}^2}$ is a Markov random field iff

$$(1.4) \quad \Gamma(z, z'') = \phi(z, (x', y)) \Gamma((x', y), z''), \text{ for all } x'' \leq x' \leq x, \text{ and}$$

$$(1.5) \quad \Gamma(z, z'') = \phi(z, (x, y')) \Gamma((x, y'), z''), \text{ for all } y'' \leq y' \leq y,$$

where $z = (x, y)$, $z'' = (x'', y'')$.

In this case the function ϕ verifies

$$(1.6) \quad \phi(z, z'') = \phi(z, z') \phi(z', z'') \text{ if } z'' \leq z' \leq z.$$

As a consequence of this proposition we obtain that under condition (1.2) definition 1.1. is equivalent, in the Gaussian case, to the Markov property introduced by H. Korezlioglu in [3].

Proof: The Markov property, in the Gaussian case, is equivalent to the existence, for all $z' \leq z$, of real numbers $\lambda_1, \lambda_2, \lambda_3$ such that

$$E[X(z)/G_{z'}] = \lambda_1 X(x, y') + \lambda_2 X(z') + \lambda_3 X(x', y);$$

that means

$$(1.7) \quad \Gamma(z, z'') = \lambda_1 \Gamma((x, y'), z'') + \lambda_2 \Gamma(z', z'') + \lambda_3 \Gamma((x', y), z'')$$

for all $z' \in Q_{z''}$.

Then, it is immediate that conditions (1.4) and (1.5) imply (1.7) and the reciprocal follows taking $x' \rightarrow -\infty$ or $y' \rightarrow -\infty$ in (1.7) and applying property (1.2). \square

In order to obtain a characterization of X in the Markov case, we need several smoothing hypotheses about its covariance function.

H1.- $\Gamma(z, z')$ is a continuous function and the set $D = \{z \in \mathbb{R}^2 / \Gamma(z) > 0\}$ is either \mathbb{R}^2 or $Q_{z_0}^c = \{z \in \mathbb{R}^2 / z \gg z_0\}$ for a certain point z_0 , where $z_0 \ll z$ means $x_0 < x$ and $y_0 < y$.

H2.- There exists a positive continuous function $f: \bar{D} \rightarrow \mathbb{R}$ such that $\phi(z, z') = f(z) f(z')^{-1}$ for all $z' \leq z, z', z \in D$.

H3.- $K(z) = f(z)^{-2} \Gamma(z)$ is an absolutely continuous function on D.

Theorem 1.1.- If the covariance function $\Gamma(z, z')$ of the process X verifies the previous hypotheses H1, H2, H3, X is a Markov random

field iff there exist a Brownian measure W on \mathbb{R}^2 , a continuous function $\phi_1(z)$ on \mathbb{R}^2 and a square integrable function $\phi_2(z) \in L^2(\mathbb{R}^2)$ such that

$$(1.8) \quad X(z) = \phi_1(z) \cdot \int_{\mathbb{R}^2} \phi_2(\zeta) dW(\zeta).$$

Proof: The random function $Y(z) = f(z)^{-1} \cdot X(z)$ if $z \in D$, $Y(z) = 0$ if $z \notin D$, has a covariance function

$$E[Y(z) \cdot Y(z')] = f(z \wedge z')^{-2} \cdot \Gamma(z \wedge z'),$$

which satisfies (iii) of Proposition 1.1, because of hypothesis H3.

Therefore, there exist a Brownian measure W and a function $\phi_2(z) \in L^2(\mathbb{R}^2)$ such that $Y(z) = \int_{\mathbb{R}^2} \phi_2(\zeta) dW(\zeta)$. It suffices, then, to take $\phi_1(z) = f(z)$.

Conversely, it is clear that every random field $X(z)$ given by (1.8) satisfies the Markov property. \square

Suppose that for all $z = (x, y)$, $z' = (x', y')$, $z' \leq z$, $z, z' \in D$ there exist the following partial derivatives

$$b(z) = -\frac{\partial \phi(z, z')}{\partial x^+} \Big|_{z=z'}, \quad a(z) = -\frac{\partial \phi(z, z')}{\partial y^+} \Big|_{z=z'}, \quad d(z) = \frac{\partial^2 \phi(z, z')}{\partial x^+ \partial y^+} \Big|_{z=z'}.$$

Then, using property (1.6) we have

$$\frac{\partial \phi(z, z')}{\partial x} = -b(z) \phi(z, z'), \quad \frac{\partial \phi(z, z')}{\partial y} = -a(z) \phi(z, z'),$$

$$\frac{\partial^2 \phi(z, z')}{\partial x \partial y} = d(z) \phi(z, z'), \quad d(z) = a(z)b(z) - \frac{\partial a(z)}{\partial x} \quad \text{and}$$

$$\frac{\partial a(z)}{\partial x} = \frac{\partial b(z)}{\partial y} \quad \text{for all } z' \leq z, \quad z', z \in D.$$

In this situation, the function $\phi_2(z)$ can be calculated as follows:

$$\phi_2(z) = \left[\frac{\partial^2 E Y(z)}{\partial x \partial y} \right]^{\frac{1}{2}} = f(z)^{-1} \cdot q(z), \quad \text{where}$$

$$q(z)^2 = \frac{\partial^2 \Gamma(z)}{\partial x \partial y} + 2a(z) \frac{\partial \Gamma(z)}{\partial x} + 2b(z) \frac{\partial \Gamma(z)}{\partial y} + (4a(z)b(z) + 2\frac{\partial b(z)}{\partial y}) \Gamma(z).$$

These random fields can also be considered as solutions of linear hyperbolic partial differential equations:

$$\frac{\partial^2 X}{\partial x \partial y} + a(z) \frac{\partial X}{\partial x} + b(z) \frac{\partial X}{\partial y} + c(z)X = q(z) \xi(z),$$

with the conditions $c=ab + \frac{\partial a}{\partial x}$ and $\frac{\partial a}{\partial x} = \frac{\partial b}{\partial y}$, where $\xi(z)$ is a white noise distributed on \mathbb{R}_+^2 .

We can attach a more precise meaning to these equations within the frame of the generalized stochastic processes theory.

As it is shown in [2], the only stationary Gaussian Markov process $\{X_{st}\}_{st \in \mathbb{R}^2}$ with non vanishing absolutely continuous variance function $\Gamma(z)$ is the two-parameter Ornstein-Uhlenbeck process, that is $X_{st} = \int_{R_{st}} \exp[-\alpha(s-x) - \beta(t-y)] dW_{xy}$, where $\alpha, \beta > 0$.

Besides, using the rules of Itô's stochastic differential calculus in each coordinate, we obtain the following differential expressions for X:

$$\begin{aligned} d_1 X &= -b(z) X(z) dx + \phi_1(z) \alpha_1(z) W_y^{(1)}(dx), \\ d_2 X &= -a(z) X(z) dy + \phi_1(z) \alpha_2(z) W_x^{(2)}(dy). \end{aligned} \tag{1.9}$$

In these formulae $d_1 X = X(x+dx, y) - X(x, y)$ and $d_2 X = X(x, y+dy) - X(x, y)$ represent the differential increments in each coordinate, and $\alpha_1(z), \alpha_2(z)$ are

$$\alpha_1(z) = \left[\int_{-\infty}^y \phi_2^2(x, \eta) d\eta \right]^{1/2}, \quad \alpha_2(z) = \left[\int_{-\infty}^x \phi_2^2(\xi, y) d\xi \right]^{1/2}.$$

The functions $W_y^{(1)}(A), W_x^{(2)}(A)$ defined by

$$\begin{aligned} W_y^{(1)}(A) &= \int_A \int_{-\infty}^y \frac{\phi_2(\xi, \eta)}{\alpha_1(\xi, y)} dW(\xi, \eta), \\ W_x^{(2)}(A) &= \int_A \int_{-\infty}^x \frac{\phi_2(\xi, \eta)}{\alpha_2(x, \eta)} dW(\xi, \eta), \end{aligned}$$

A being a Borel set in \mathbb{R} , are ordinary Wiener measures when both variables y and x are fixed.

In particular, notice that $X(z)$ is a diffusion process in each coordinate.

In the same way, the rules of the two parameter differential stochastic calculus, developed in [1], and [5] give rise to the differential expression

$$(1.10) \quad \begin{aligned} dX = & q(z) dW(z) + d(z) X(z) dz - a(z) \phi_1(z) \alpha_1(z) dy W_y^{(1)}(dx) \\ & - b(z) \phi_1(z) \alpha_2(z) dx W_x^{(2)}(dy), \end{aligned}$$

where dX denotes the increment $X(x+dx, y+dy) - X(x, y+dy) - X(x+dx, y) + X(x, y)$.

This situation leads us to introduce some diffusion conditions for two parameter random Markov fields in order to consider the process given by (1.8) as a two parameter diffusion process and to provide some elements to study and characterize random Markov fields in the non Gaussian case.

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Let $X = \{X(z) \mid z \in \mathbb{R}_+^2\}$ be a two parameter random Markov field, there exist a function

$$P(z_1, \bar{w}, w, w_2; z_2, A),$$

defined for all $\bar{w} = (w_1, w, w_2) \in \mathbb{R}^3$, $z_1, z_2 \in \mathbb{R}_+^2$, $z_1 \leq z_2$, and Borel sets A , for which the following properties hold:

- (1) $P(z_1, \bar{w}; z_2, A)$ is a Borel function of \bar{w} ,
- (2) $P(z_1, \bar{w}; z_2, \cdot)$ is a probability for fixed z_1, z_2, \bar{w} ,
- (3) $P[X(z_2) \in A \mid X(x_1, y_2) = w_1, X(z_1) = w, X(x_2, y_1) = w_2] = P(z_1, \bar{w}; z_2, A)$, w.p.1.

This function will be called the transition probability for X .

It also satisfies an equation of the Chapman-Kolmogorov type, that is, given a fixed point $\zeta = (\xi, \eta)$ such that $z_1 \leq \zeta \leq z_1$, we have

$$(2.1) \quad \begin{aligned} P(z_1, \bar{w}; z_2, A) = & \iint_{\mathbb{R}^3} P(\zeta, \bar{v}; z_2, A) \cdot P((x_1, \eta), (w_1, w_1^1, v); (\xi, \eta_2), dv_1) \cdot \\ & P((\xi, \eta_2), (v, w_2^1, w_2); (x_2, \eta), dv_2) \cdot P(z_1, (w_1^1, w, w_2^1); \zeta, dv). \end{aligned}$$

This relation must be true for all $w_1', w_2' \in \mathbb{R}$.

If we know the transition probabilities $P(z_1, \bar{w}; z_2, A)$ and the distributions of $\{X(o, y), o \leq y\}$ and $\{X(x, o), o \leq x\}$, we can deduce all the finite dimensional distributions of X by using (2.1) as in the one parameter case.

If X vanishes on the axes, then X is a Markov process in each coordinate and its transition probabilities are:

$$(2.2) \quad P_y(x_1, w, x_2, A) = P[X(x_2, y) \in A / X(x_1, y) = w] = P((x_1, o), (w, o, o); (x_2, y), A),$$

where y is fixed, and

$$(2.3) \quad P_x(y_1, w, y_2, A) = P[X(x, y_2) \in A / X(x, y_1) = w] = P((o, y_1), (o, o, w); (x, y_2), A),$$

where x is fixed.

We assume in the following that X vanishes on the axes and has continuous sample paths. We also suppose the existence of a density $p(z_1, \bar{w}; z_2, u)$.

Let $z = (x, y)$ be a fixed point of \mathbb{R}_+^2 and let us consider the increments

$$\begin{aligned} X(\Delta_1) &= X(x + \Delta x, y) - X(z) \\ X(\Delta_2) &= X(x, y + \Delta y) - X(z) \\ X(\Delta) &= X(z') - X(x + \Delta x, y) - X(x, y + \Delta y) + X(z), \end{aligned}$$

where $z' = (x + \Delta x, y + \Delta y)$ and $\Delta x > 0, \Delta y > 0$.

The stochastic differentials for the random Markov field X we have obtained in the Gaussian case have suggested us to introduce some conditions for X to be a two parameter diffusion process.

For the sake of simplicity we will omit truncations of the moments, stating only the usual conditions in strong sense.

Definition 2.1. - A random Markov field X is called a diffusion process in each coordinate iff:

$$(2.4) \quad \lim_{\Delta x \rightarrow 0} \frac{E[X(\Delta_1)^k / X(z) = w]}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{1}{\Delta x} \int_{\mathbb{R}} (w_2 - w)^k p_y(x, w, x + \Delta x, w_2) dw_2 = \begin{cases} a_1(z, w) & \text{if } k=1 \\ b_1(z, w) & \text{if } k=2 \\ 0 & \text{if } k>2 \end{cases}$$

$$(2.5) \quad \lim_{\Delta y \rightarrow 0} \frac{E[X(\Delta_2)^k / X(z) = w]}{\Delta y} = \lim_{\Delta y \rightarrow 0} \frac{1}{\Delta y} \int_{\mathbb{R}} (w_1 - w)^k p_x(y, w, y + \Delta y, w_1) dw_1 = \begin{cases} a_2(z, w) & \text{if } k=1 \\ b_2(z, w) & \text{if } k=2 \\ 0 & \text{if } k>2 \end{cases}$$

where a_1, b_1, a_2, b_2 are continuous functions, and represent the coefficients of diffusion and displacement in each coordinate.

Let us introduce the function

$$p(z, w; z', (w_1, u, w_2)) = p(z, \bar{w}; z', u) \cdot p_Y(x, w, x + \Delta x, w_2) \cdot p_X(y, w, y + \Delta y, w_1)$$

for all $z \leq z'$, $\bar{w} = (w_1, w, w_2) \in R^3$, $u \in R$,

which verifies, using the Markov property, that

$$p(z, w; z', (w_1, u, w_2)) = P [X(z') = u, X(x, y') = w_1, X(x', y) = w_2 / X(z) = w],$$

w.p.1.

Definition 2.2.- A random Markov field X will be called a two parameter diffusion process iff it is a diffusion process in each coordinate and possesses the following properties:

$$\lim_{\Delta x, \Delta y \rightarrow 0} \frac{E[X(\Delta)^k / X(z) = w]}{\Delta x \cdot \Delta y} = \lim_{\Delta x, \Delta y \rightarrow 0} \frac{1}{\Delta x \cdot \Delta y} \iiint_{R^3} (u - w_1 - w_2 + w)^k$$

$$(2.6) \quad p(z, w; z', (w_1, u, w_2)) dw_1 du dw_2 = \begin{cases} a(z, w) & \text{if } k=1 \\ b(z, w) & \text{if } k=2 \\ 0 & \text{if } k>2 \end{cases}.$$

$$\lim_{\Delta x, \Delta y \rightarrow 0} \frac{E[X(\Delta)^k X(\Delta_1)^i X(\Delta_2)^j / X(z) = w]}{\Delta x \cdot \Delta y} = \lim_{\Delta x, \Delta y \rightarrow 0} \frac{1}{\Delta x \cdot \Delta y} \iiint_{R^3} (u - w_1 - w_2 + w)^k \cdot (w_1 - w)^j$$

$$(2.7) \quad \cdot (w_2 - w)^i \cdot p(z, w; z', (w_1, u, w_2)) dw_1 du dw_2 = \begin{cases} c_1(z, w) & \text{if } k=i=1, j=0, \\ c_2(z, w) & \text{if } k=j=1, i=0, \\ d(z, w) & \text{if } k=i=j=1, \\ 0 & \text{if } k>1 \text{ and } i+j>1. \end{cases}$$

$a(z, w)$ and $b(z, w)$ will be called, respectively the two parameter coefficients of diffusion and displacement, and $c_1(z, w)$, $c_2(z, w)$, $d(z, w)$ will be called mixed diffusion coefficients. All of them are supposed continuous functions of (z, w) .

Proposition 2.1.- If X is a two parameter diffusion process, we have

$$\lim_{\Delta x, \Delta y \rightarrow 0} \frac{E[X(\Delta_1)^i X(\Delta_2)^j / X(z) = w]}{\Delta x \cdot \Delta y} = \begin{cases} a_1(z, w) \cdot a_2(z, w) & \text{if } i=j=1, \\ a_1(z, w) \cdot b_2(z, w) & \text{if } i=1, j=2, \\ b_1(z, w) \cdot a_2(z, w) & \text{if } i=2, j=1, \\ b_1(z, w) \cdot b_2(z, w) & \text{if } i=j=2, \\ 0 & \text{if } i>2 \text{ or } j>2. \end{cases}$$

In fact, the Markov property implies

$$E[X(\Delta_1)^i X(\Delta_2)^j / X(z)=w] = E[X(\Delta_1)^i / X(z)=w] \cdot E[X(\Delta_2)^j / X(z)=w].$$

Finally, the main result of this section is a "forward equation" for the evolution of the conditional probability density.

Theorem 2.1.- (Kolmogorov's Forward Equation). Let X be a two parameter diffusion process such that the transition probability density $p(z_1, \bar{w}; z_2, u)$ has the partial derivatives

$$\frac{\partial^2 p}{\partial x \partial y}, \frac{\partial p}{\partial u}, \frac{\partial^2 p}{\partial u^2}, \frac{\partial^3 p}{\partial u^3} \text{ and } \frac{\partial^4 p}{\partial u^4} \text{ continuous and also bounded in } (z, u)$$

for each fixed $z_1 \in T$, $z_1 \leq z$, $\bar{w} \in R^3$. We also assume that $\frac{\partial^2 p}{\partial x \partial y}$ is

uniformly continuous in z with respect to (w_1, w_2) and u , that it is continuous in (w_1, w_2) , and bounded

$$\left| \frac{\partial^2 p}{\partial x \partial y} \right| \leq g(u) \text{ for fixed } z_1 \text{ and } w,$$

$g(u)$ being a Lebesgue integrable function.

Then we have,

$$(2.8) \quad \frac{\partial^2 p}{\partial x \partial y} = - \frac{\partial (p M_1)}{\partial u} + \frac{1}{2} \frac{\partial^2 (p M_2)}{\partial u^2} - \frac{1}{2} \frac{\partial^3 (p M_3)}{\partial u^3} + \frac{1}{4} \frac{\partial^4 (p M_4)}{\partial u^4}$$

where the infinitesimal moments of order i , $M_i(z, u)$, $i=1,2,3,4$, are given by

$$(2.9) \quad M_i(z, u) = \sum_{\substack{\alpha+\beta+\gamma=i \\ \alpha, \beta, \gamma \in N}} \lim_{\Delta x, \Delta y \rightarrow 0} \frac{E[X(\Delta)^{\gamma} X(\Delta_1)^{\alpha} X(\Delta_2)^{\beta} / X(z)=u]}{\Delta x \cdot \Delta y},$$

that is,

$$\begin{aligned} M_1 &= a \\ M_2 &= b + 2c_1 + 2c_2 + 2a_1 a_2 \\ M_3 &= a_1 b_2 + a_2 b_1 + 2d \\ M_4 &= b_1 b_2. \end{aligned}$$

We also suppose the terms in the limit (2.9) to be bounded by a finite constant k_i independent of (z, u) .

Proof: Let $f: \mathbb{R} \rightarrow \mathbb{R}$ be infinitely differentiable with compact support, and, for fixed (z, \bar{w}) , consider the function defined by $\varphi(z) = E[f(X(z)) / X(z_1) = w, X(x_1, y) = w_1, X(x, y_1) = w_2] = \int_{\mathbb{R}} f(u) p(z_1, \bar{w}; z, u) du$.

We know there exist

$$(2.10) \quad \frac{\partial^2 \varphi}{\partial x \partial y} = \int_{\mathbb{R}} f(u) \frac{\partial^2 p(z_1, \bar{w}; z, u)}{\partial x \partial y} du,$$

and $\frac{\partial^2 \varphi}{\partial x \partial y}$ is continuous and bounded in (w_1, w_2, z) for fixed (z_1, \bar{w}) .

Therefore, diffusion conditions in each coordinate imply

$$(2.11) \quad \frac{\partial^2 \varphi}{\partial x \partial y}(w_1, w_2, z) = \lim_{\Delta x, \Delta y \rightarrow 0} \iint_{\mathbb{R}^2} \frac{\partial^2 \varphi}{\partial x \partial y}(w'_1, w'_2, z) P_{Y_1}(x, w_2; x', w'_2) P_{X_1}(y, w_1; y', w'_1) dw'_1 dw'_2,$$

where $x' = x + \Delta x$ and $y' = y + \Delta y$.

Using the mean value theorem,

$$\frac{\varphi(z') - \varphi(x', y) - \varphi(x, y') + \varphi(z)}{\Delta x \cdot \Delta y}(w'_1, w'_2) = \frac{\partial^2 \varphi}{\partial x \partial y}(w'_1, w'_2, z''),$$

where $z \leq z'' \leq z'$.

Uniform continuity of $\frac{\partial^2 \varphi}{\partial x \partial y}$ in z gives

$$\lim_{\Delta x, \Delta y \rightarrow 0} \iint_{\mathbb{R}^2} \left[\frac{\partial^2 \varphi}{\partial x \partial y}(w'_1, w'_2, z) - \frac{\partial^2 \varphi}{\partial x \partial y}(w'_1, w'_2, z'') \right]$$

$$P_{Y_1}(x, w_2; x', w'_2) P_{X_1}(y, w_1; y', w'_1) dw'_1 dw'_2 = 0,$$

then from (2.11) we obtain

$$(2.12) \quad \lim_{\Delta x, \Delta y \rightarrow 0} \frac{1}{\Delta x \Delta y} \iint_{\mathbb{R}^2} [\varphi(z') - \varphi(x', y) - \varphi(x, y') + \varphi(z)](w'_1, w'_2) \cdot$$

$$P_{Y_1}(x, w_2; x', w'_2) \cdot P_{X_1}(y, w_1; y', w'_1) dw'_1 dw'_2 = \frac{\partial^2 \varphi}{\partial x \partial y}(w_1, w_2, z).$$

Using Chapman-Kolmogorov's equation, we write

$$\begin{aligned}
 & [\varphi(z') - \varphi(x', y) - \varphi(x, y') + \varphi(z)] (w'_1, w'_2) = \\
 & = \int_{\mathbb{R}} f(u') p(z_1, (w'_1, w, w'_2); z', u') du' - \int_{\mathbb{R}} f(u_2) p(z_1, (w_1, w, w'_2); (x', y), u_2) du_2 - \\
 & - \int_{\mathbb{R}} f(u_1) p(z_1, (w'_1, w, w_2); (x, y'), u_1) du_1 + \int_{\mathbb{R}} f(u) p(z_1, \bar{w}; z, u) du = \\
 & = \int_{\mathbb{R}} f(u') [\int_{\mathbb{R}} \int_{\mathbb{R}} \int_{\mathbb{R}} p(z, (u_1, u, u_2); z', u') p((x_1, y), (w'_1, w_1, u); (x, y'), u_1) \\
 & p((x, y_1), (u, w_2, w'_2); (x', y), u_2) \cdot p(z_1, \bar{w}; z, u) du_1 du du_2] du' - \\
 & - \int_{\mathbb{R}} f(u_2) [\int_{\mathbb{R}} p((x, y_1), (u, w_2, w'_2); (x', y), u_2) p(z_1, \bar{w}; z, u) du] du_2 - \\
 & - \int_{\mathbb{R}} f(u_1) [\int_{\mathbb{R}} p((x_1, y), (w'_1, w_1, u); (x, y'), u_1) p(z_1, \bar{w}; z, u) du] du_1 + \\
 & + \int_{\mathbb{R}} f(u) p(z_1, \bar{w}; z, u) du.
 \end{aligned}$$

If we substitute in (2.12) taking into account that

$$\begin{aligned}
 p_Y(x, u; x', u_2) &= \int_{\mathbb{R}} p((x, y_1), (u, w_2, w'_2); (x', y), u_2) p_{Y_1}(x, w_2; x', w'_2) dw'_2, \text{ and} \\
 p_X(y, u; y', u_1) &= \int_{\mathbb{R}} p((x_1, y), (w'_1, w_1, u); (x, y'), u_1) p_{X_1}(y, w_1; y', w'_1) dw'_1,
 \end{aligned}$$

we have

$$\begin{aligned}
 \frac{\partial^2 \varphi}{\partial x \partial y}(w_1, w_2, z) &= \lim_{\Delta x, \Delta y \rightarrow 0} \frac{1}{\Delta x \Delta y} \int_{\mathbb{R}} E[f(X(z') - f(X(x', y)) - f(X(x, y')) + \\
 & + f(X(z)) / X(z)=u] \cdot p(z_1, \bar{w}; z, u) du.
 \end{aligned}$$

Using a Taylor expansion of f and the hypotheses for the moments $M_i(z, u)$, we obtain

$$\begin{aligned}
 \frac{\partial^2 \varphi}{\partial x \partial y} &= \int_{\mathbb{R}} [M_1(z, u) f'(u) + \frac{1}{2} M_2(z, u) f''(u) + \frac{1}{2} M_3(z, u) f'''(u) + \frac{1}{4} M_4(z, u) f^{IV}(u)] \\
 & p(z_1, \bar{w}; z, u) du.
 \end{aligned}$$

Finally, integrating by parts and using $f^{(k)}(\pm\infty)=0$, we conclude the theorem proof by means of the identification with formula (2.10). \square

- 3 -

Let $X = \{X(z)\}_{z \in \mathbb{R}_+^2}$ be a two-parameter diffusion process and $f(z, u)$ a monotone function in $u \in \mathbb{R}$ for all $z \in \mathbb{R}_+^2$. Let $g(z, w)$ denote the inverse function of $f(z, u)$.

Then, the random field $Y(z) = f(z, X(z))$ is also a Markov random process with transition probability $\bar{P}(z_1, \bar{w}, z_2, A)$ related to the one of X by

$$\bar{P}(z_1, \bar{w}; z_2, A) = P(z_1, (g((x_1, y_2), w_1), g(z, w), g((x_2, y_1), w_2))); z_2, g(z_2, A)).$$

If f is differentiable and bounded enough (i. e.,

$$\frac{\partial^4 f}{\partial u^4}, \frac{\partial^3 f}{\partial x \partial u^2}, \frac{\partial^3 f}{\partial y \partial u^2}, \frac{\partial^2 f}{\partial x \partial y} \text{ and } f \text{ is continuous and bounded), then}$$

Y is a two parameter diffusion process. Boundness hypotheses can be eliminated weakening diffusion conditions by means of truncations.

The coefficients for the diffusion process Y in each coordinate are given by

$$\bar{a}_1(z, w) = \frac{\partial f}{\partial x}(z, u) + a_1(z, u) \frac{\partial f}{\partial u}(z, u) + \frac{1}{2} b_1(z, u) \frac{\partial^2 f}{\partial u^2}(z, u) = D_1(f)(z, u),$$

$$\bar{b}_1(z, w) = b_1(z, u) \left[\frac{\partial f}{\partial u}(z, u) \right]^2,$$

$$\bar{a}_2(z, w) = \frac{\partial f}{\partial y}(z, u) + a_2(z, u) \frac{\partial f}{\partial u}(z, u) + \frac{1}{2} b_2(z, u) \frac{\partial^2 f}{\partial u^2}(z, u) = D_2(f)(z, u),$$

$$\bar{b}_2(z, w) = b_2(z, u) \left[\frac{\partial f}{\partial u}(z, u) \right]^2,$$

where $u = g(z, w)$ and D_1, D_2 denote the diffusion operators in each coordinate. Using a Taylor expansion of f we can also calculate two parameter coefficients:

$$\bar{a}(z, w) = D_1 \left(\frac{\partial f}{\partial y} \right) + D_2 \left(\frac{\partial f}{\partial x} \right) - \frac{\partial^2 f}{\partial x \partial y} + M_1 \frac{\partial f}{\partial u} + \frac{1}{2} M_2 \frac{\partial^2 f}{\partial u^2} + \frac{1}{2} M_3 \frac{\partial^3 f}{\partial u^3} + \frac{1}{4} M_4 \frac{\partial^4 f}{\partial u^4},$$

$$\bar{b}(z, w) = b \cdot \left[\frac{\partial f}{\partial u} \right]^2 + b_1 b_2 \left[\frac{\partial^2 f}{\partial u^2} \right]^2 + 2d \cdot \frac{\partial f}{\partial u} \cdot \frac{\partial^2 f}{\partial u^2},$$

$$\bar{c}_1(z, w) = \frac{\partial f}{\partial u} \cdot \left[b_1 \cdot D_2 \left(\frac{\partial f}{\partial u} \right) + c_1 \cdot \frac{\partial f}{\partial u} + d \cdot \frac{\partial^2 f}{\partial u^2} \right],$$

$$\bar{c}_2(z, w) = \frac{\partial f}{\partial u} \cdot \left[b_2 \cdot D_1 \left(\frac{\partial f}{\partial u} \right) + c_2 \cdot \frac{\partial f}{\partial u} + d \cdot \frac{\partial^2 f}{\partial u^2} \right],$$

$$\bar{d}(z, w) = d \cdot \left[\frac{\partial f}{\partial u} \right]^3 + b_1 b_2 \left[\frac{\partial f}{\partial u} \right]^2 \cdot \frac{\partial^2 f}{\partial u^2},$$

where we have omitted for simplicity the dependence with respect to (z, u) in the second term.

For example, given the coefficients of the two parameter Wiener process $W = \{W(z)\}_{z \in \mathbb{R}_+^2}$ as a diffusion process:

$$a_1 = a_2 = 0, \quad b_1 = y, \quad b_2 = x,$$

$$b = 1, \quad a = c_1 = c_2 = d = 0,$$

we can calculate by means of the preceding formulas the coefficients of $X(z) = f(z, W(z))$:

$$\bar{a}_1 = \frac{\partial f}{\partial x} + \frac{1}{2} y \frac{\partial^2 f}{\partial u^2} = D_1(f), \quad \bar{b}_1 = y \cdot \left[\frac{\partial f}{\partial u} \right]^2,$$

$$\bar{a}_2 = \frac{\partial f}{\partial y} + \frac{1}{2} x \frac{\partial^2 f}{\partial u^2} = D_2(f), \quad \bar{b}_2 = x \cdot \left[\frac{\partial f}{\partial u} \right]^2,$$

$$D_2(f),$$

$$\cdot \left[\frac{\partial^2 f}{\partial u^2} \right]^2,$$

These results can be compared with the differential representation of the random field $X(z)$ obtained by using the rules of the two parameter stochastic differential calculus [4]:

$$d_1(X(z)) = D_1(f) dx + \sqrt{y} \cdot \frac{\partial f}{\partial u} W_y^{(1)}(dx),$$

$$d_2(X(z)) = D_2(f) dy + \sqrt{x} \cdot \frac{\partial f}{\partial u} W_x^{(2)}(dy),$$

$$dX(z) = \frac{\partial f}{\partial u} \cdot dW + \sqrt{xy} \frac{\partial^2 f}{\partial u^2} W_y^{(1)}(dx) W_x^{(2)}(dy) + y \cdot D_2\left(\frac{\partial f}{\partial u}\right) dy W_y^{(1)}(dx) + \sqrt{x} \cdot D_1\left(\frac{\partial f}{\partial u}\right) dx W_x^{(2)}(dy) + (D_1 \circ D_2)(f) dx dy,$$

where $W_y^{(1)}(x) = \frac{W(x,y)}{y}$, $W_x^{(2)}(y) = \frac{W(x,y)}{x}$ are Brownian motions in x and y respectively.

Finally, the Gaussian random function $X(z) = \int_0^x \int_0^y \vartheta_2(\alpha) dW(\alpha)$, $z = (x,y)$, introduced in Section 1, is also a two parameter diffusion process with coefficients

$$\begin{aligned} a_1 &= -b u, & b_1 &= \vartheta_1^2 \alpha_1^2, \\ a_2 &= -a u, & b_2 &= \vartheta_1^2 \alpha_2^2, \\ a &= d u, & b &= q^2, & c_1 &= -a \vartheta_1^2 \alpha_1^2, & c_2 &= -b \vartheta_1^2 \alpha_2^2, & d &= 0. \end{aligned}$$

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