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# On smoothing conditions of multivariate splines

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#### Abstract

Let T be a k-simplex in  $\mathbb{R}^s$ , where  $0 \leq k < n$ , and let  $S_a$  and  $S_b$  be two adjacent s-simplices with  $T = S_a \cap S_b$ . Suppose that  $F(x) \in C(S_a \cup S_b)$  with

$$F(x)|_{S_a} = P_n(x),$$
  
$$F(x)|_{S_b} = Q_n(x),$$

where  $P_n$  i  $Q_n$  are Bezier polynomials in  $\mathbb{R}^s$  with total degree n. The conditions, which must be required to function F be in class  $C^r$  across T, are introduced by C.K. Chui and M. Lai ([3], [4]). In the present note the improvement of those conditions is obtained. As an application, algorithm for computation of polynomial coefficients is shown.

### Introduction

Let  $x^0, x^1, x^2, \dots, x^s$  be linear independent points in  $\mathbb{R}^s$ . Then its convex hull

(1) 
$$\langle x^0, \dots, x^s \rangle = \left\{ \sum_{i=0}^s \lambda_i x^i : \sum_{i=0}^s \lambda_i = 1, \lambda_0, \dots, \lambda_s \ge 0 \right\}$$

is a simplex. It is called an s-simplex. Then any  $x \in \mathbb{R}^s$  can be identified with an (s+1)-tuple  $(\lambda_0, \ldots, \lambda_s)$  where

(2) 
$$\lambda_i = \lambda_i(x) = \frac{\operatorname{vol}_s\langle x^0, \dots, x^{i-1}, x, x^{i+1}, \dots, x^s \rangle}{\operatorname{vol}_s\langle x^0, \dots, x^s \rangle},$$

and

(3) 
$$\operatorname{vol}_{s}\langle x^{0}, \dots, x^{s} \rangle = \frac{1}{s!} \begin{vmatrix} 1 & x_{1}^{0} & \dots & x_{s}^{0} \\ \dots & \dots & \dots \\ 1 & x_{1}^{s} & \dots & x_{s}^{s} \end{vmatrix},$$

where  $x^i = (x_1^i, \dots, x_s^i)$  and  $x = (x_1, \dots, x_s)$ . The numbers  $\lambda_0, \dots, \lambda_s$  are called the barycentric coordinate of x relative to the simplex  $\langle x^0, \dots, x^s \rangle$ . Since each  $\lambda_i = \lambda_i(x)$  and by using the notation  $\lambda^\beta = \lambda_0^{\beta_0} \dots \lambda_s^{\beta_s}$  and  $\beta! = \beta_0! \dots \beta_s!$  for any  $\beta = (\beta_0, \dots, \beta_s) \in \mathbb{Z}_+^{s+1}$ , where  $\mathbb{Z}_+ = \{0, 1, \dots\}$ , the Bezier polynomial is defined by

(4) 
$$P_n(x) = \sum_{|\beta|=n} a_{\beta} \Phi_{\beta}^n(\lambda),$$

where  $\Phi_{\beta}^{n}(\lambda)$  are the Bernstein polynomials of degree n

(5) 
$$\Phi_{\beta}^{n}(\lambda) = \frac{n!}{\beta!} \lambda^{\beta}, \quad |\beta| = \beta_0 + \ldots + \beta_s = n.$$

The set  $\left\{ \left( \frac{\beta_0}{n}, \cdots, \frac{\beta_s}{n}, a_{\beta} \right) : |\beta| = n \right\}$  is called the Bezier net of  $P_n(x)$ . Let  $T = \langle x^0, \dots, x^k \rangle$  be a k-simplex in  $\mathbb{R}^s$  where  $0 \le k < s$ , and let

(6) 
$$S_a = \langle x^0, \dots, x^k, x^{k+1}, \dots, x^s \rangle,$$
$$S_b = \langle x^0, \dots, x^k, y^{k+1}, \dots, y^s \rangle,$$

be two adjacent s-simplices with  $T = S_a \cap S_b$ . Suppose that  $F(x) \in C(S_a \cup S_b)$  with

(7) 
$$F(x)|_{S_a} = P_n(x) = \sum_{|\alpha|=n} a_{\alpha} \Phi_{\alpha}^n (\lambda_0(x), \dots, \lambda_s(x)),$$
$$F(x)|_{S_b} = Q_n(x) = \sum_{|\beta|=n} a_{\beta} \Phi_{\beta}^n (\eta_0(x), \dots, \eta_s(x)),$$

where  $\lambda = (\lambda_0, \dots, \lambda_s)$  and  $\eta = (\eta_0, \dots, \eta_s)$  are the barycentric coordinate of x relative to  $S_a$  and  $S_b$  respectively.

Let  $s_i(\alpha) = (\alpha_0, \dots, \alpha_{i-1}, \alpha_i + 1, \alpha_{i+1}, \dots, \alpha_s)$  and  $\Delta_{ij} a_{\alpha} = a_{s_i\alpha} - a_{s_j\alpha}$ . Using above notation, one can formulate the following smoothing conditions:

Theorem 1 (C.K. Chui and M.J. Lai)

Let

(8) 
$$c_{ji} = \frac{\operatorname{vol}_s \langle x^0, \dots, x^{i-1}, y^j, x^{i+1}, \dots, x^s \rangle}{\operatorname{vol}_s \langle x^0, \dots, x^s \rangle}.$$

Then for any  $r \in \mathbb{Z}_+$ ,  $F(x) \in C^r(S_a \cup S_b)$  if and only if

(9) 
$$\Delta_{k+1,0}^{\gamma_{k+1}} \dots \Delta_{s,0}^{\gamma_s} b_{\alpha_0 \dots \alpha_k 0 \dots 0}$$

$$= \left( \sum_{i=1}^s c_{k+1,i} \ \Delta_{i0} \right)^{\gamma_{k+1}} \dots \left( \sum_{i=1}^s c_{s,i} \ \Delta_{i0} \right)^{\gamma_s} a_{\alpha_0 \dots \alpha_k 0 \dots 0}$$

for all  $\gamma_{k+1} + \ldots + \gamma_s = l$ ,  $\alpha_0 + \ldots + \alpha_k = n - l$ , and  $l = 0, \ldots, r$ .

### Results

Let  $E_i$   $(0 \le i < s)$  be the partial shift operator defined by  $E_i a_{\alpha} = a_{s_i\alpha}$ . Thus the Bezier polynomial (4) can be expressed in terms of these operators by

(10) 
$$P_n(x) = \left(\sum_{i=0}^s \lambda_i E_i\right)^n a_{0,\dots,0},$$

where  $\lambda_0, \lambda_1, \dots, \lambda_s$  are barycentric coordinates of x (see [1] and [2]). The right side of equality (10) may be evaluated by recursion formula:

(11) 
$$\left(\sum_{i=0}^{s} \lambda_i E_i\right)^n a_{0,\dots,0} = \sum_{j=0}^{s} \left(\lambda_j \left(\sum_{i=0}^{s} \lambda_i E_i\right)^{n-1} E_j a_{0,\dots,0}\right).$$

Applying above notation, the smoothing conditions (9) can be formulated as:

## Theorem 2

Under the same assumptions as in Theorem 1 the condition (9) may be replaced by the following formula

$$(12) b_{\alpha_0,\dots,\alpha_k,\gamma_{k+1},\dots,\gamma_s} = \left(\sum_{i=0}^s c_{k+1,i} E_i\right)^{\gamma_{k+1}} \cdots \left(\sum_{i=0}^s c_{s,i} E_i\right)^{\gamma_s} a_{\alpha_0,\dots,\alpha_k,0,\dots,0},$$

for all  $\gamma_{k+1} + \cdots + \gamma_s = l$ ,  $\alpha_0 + \cdots + \alpha_k = n - l$ , and  $l = 0, \dots, r$ .

*Proof.* The proof is based on the following observation: the equalities (9) form a consistent system of linear equations. Hence, it is sufficient to show that the equalities (12) are solution of this system.

First, we note that

(13) 
$$\Delta_{i,j}^n = E_i \Delta_{i,j}^{n-1} - E_j \Delta_{i,j}^{n-1} \quad \text{where} \quad \Delta_{i,j} = E_i - E_j.$$

Applying (13) to the left side of (9) we obtain:

$$\Delta_{k+1,0}^{\gamma_{k+1}} \cdots \Delta_{s,0}^{\gamma_s} B_{\alpha_0 \dots \alpha_k 0 \dots 0} 
= (E_{k+1} - E_0)^{\gamma_{k+1}} \cdots (E_s - E_0)^{\gamma_s} b_{\alpha_0 \dots \alpha_k 0 \dots 0} 
= \left(\sum_{i_{k+1}=0}^{\gamma_{k+1}} {\gamma_{k+1} \choose i_{k+1}} E_{k+1}^{i_{k+1}} (-E_0)^{\gamma_{k+1} - i_{k+1}}\right) 
\cdots \left(\sum_{i_s=0}^{\gamma_s} {\gamma_s \choose i_s} E_s^{i_s} (-E_0)^{\gamma_s - i_s}\right) b_{\alpha_0 \dots \alpha_k 0 \dots 0}.$$

Changing order of summation and using definition of  $E_i$ , expression (14) may be written as:

$$\sum_{i_{k+1}=0}^{\gamma_{k+1}} \cdots \sum_{i_{s}=0}^{\gamma_{s}} {\gamma_{k+1} \choose i_{k+1}} \cdots {\gamma_{s} \choose i_{s}} (E_{k+1})^{i_{k+1}} \cdots (E_{s})^{i_{s}}$$

$$\cdot (-E_{0})^{\gamma_{k+1}+\cdots+\gamma_{s}-i_{k+1}-\cdots-i_{s}} b_{\alpha_{0}...\alpha_{k}} 0...0$$

$$= \sum_{i_{k+1}=0}^{\gamma_{k+1}} \cdots \sum_{i_{s}=0}^{\gamma_{s}} {\gamma_{k+1} \choose i_{k+1}}$$

$$\cdots {\gamma_{s} \choose i_{s}} b_{\alpha_{0}+(\gamma_{k+1}+\cdots+\gamma_{s}-i_{k+1}-\cdots-i_{s}),\alpha_{1},...,\alpha_{k},i_{k+1},...,i_{s}}.$$

Replacing  $b_{\alpha_0+(\gamma_{k+1}+\cdots+\gamma_2-i_{k+1}-\cdots-i_s),\alpha_1,\dots,\alpha_k,i_{k+1},\dots,i_s}$  by right side of (12), formula (15) may be written as:

$$\sum_{i_{k+1}=0}^{\gamma_{k+1}} \cdots \sum_{i_{s}=0}^{\gamma_{s}} {\gamma_{k+1} \choose i_{k+1}} \cdots {\gamma_{s} \choose i_{s}} \left(\sum_{i=0}^{s} c_{k+1,i} E_{k+1}\right)^{i_{k+1}}$$

$$\cdots \left(\sum_{i=0}^{s} c_{s,i} E_{s}\right)^{i_{s}} \cdot (-E_{0})^{\gamma_{k+1}+\cdots+\gamma_{s}-i_{k+1}-\cdots-i_{s}} a_{\alpha_{0}...\alpha_{k}0...0}$$

$$= \left(\sum_{i=0}^{s} c_{k+1,i} E_{i} - E_{0}\right)^{\gamma_{k+1}} \cdots \left(\sum_{i=0}^{s} c_{s,i} E_{i} - E_{0}\right)^{\gamma_{s}} a_{\alpha_{0}...\alpha_{k}0...0}.$$

It suffices to note that if  $c_{j,i}$  are barycentric coordinate then  $1 = \sum_{i=0}^{s} c_{j,i}$ . Applying this identity to (16) we obtain right side of the equality (9):

(17) 
$$\left(\sum_{i=0}^{s} c_{k+1,i} (E_{i} - E_{0})\right)^{\gamma_{k+1}} \cdots \left(\sum_{i=0}^{s} c_{s,i} (E_{i} - E_{0})\right)^{\gamma_{s}} a_{\alpha_{0}...\alpha_{k}0...0}$$

$$= \left(\sum_{i=0}^{s} c_{k+1,i} \Delta_{i0}\right)^{\gamma_{k+1}} \cdots \left(\sum_{i=0}^{s} c_{s,i} \Delta_{i0}\right)^{\gamma_{s}} a_{\alpha_{0}...\alpha_{k}0...0}. \square$$

### **Application**

We now turn to the case k = s - 1, then conditions (11) can be expressed as:

$$b_{\alpha_0,...,\alpha_{s-1},\gamma} = \left(\sum_{i=0}^s c_{s,i} E_i\right)^{\gamma} a_{\alpha_0,...,\alpha_{s-1},0}$$
$$= \sum_{j=0}^s \left(c_{s,j} \left(\sum_{i=0}^s c_{s,i} E_i\right)^{\gamma_1} E_j a_{\alpha_0,...,\alpha_{s-1},0}\right),$$

for all  $\alpha_0 + \ldots + \alpha_{s-1} = n - \gamma$ , and  $\gamma = 0, \ldots, r$ . The above formula has following interpretation:  $b_{\alpha_0,\ldots,\alpha_{s-1},\gamma}$  may be obtained by evaluation of a Bezier polynomial of degree  $\gamma$  with some coefficients of  $P_n$  at  $y_s$ . On the other hand, recursion formula (11) provides de Casteljeu algorithm for the evaluation of  $P_n(x)$  at given point x. Let  $(\lambda_0,\ldots,\lambda_s)$  be barycentric coordinates of x. Algorithm de Casteljeu may be written as:

(19) 
$$a_{\alpha_0,\dots,\alpha_s}^0 = a_{\alpha_0,\dots,\alpha_s},$$

$$a_{\alpha_0,\dots,\alpha_s}^{\gamma} = \sum_{i=0}^s \lambda_i E_i a_{\alpha_0,\dots,\alpha_s}^{\gamma-1}, \quad \text{for } \gamma = 1,\dots,n,$$

where  $a_{\alpha_0,...,\alpha_s}^{\gamma}$   $(\gamma = 0,...,n)$  are auxiliary points with  $\sum_{i=0}^{s} \alpha_i = n - \gamma$ . It is easy to show that  $P_n(x) = a_{0,...,0}^n$  (see [5]). Applying above algorithm to point  $y_s$  we obtain the following formula:

(20) 
$$a_{\alpha_0,\dots,\alpha_s}^0 = a_{\alpha_0,\dots,\alpha_s},$$
$$a_{\alpha_0,\dots,\alpha_s}^{\gamma} = \sum_{i=0}^s c_{s,i} E_i a_{\alpha_0,\dots,\alpha_s}^{\gamma-1}, \text{ for } \gamma = 1,\dots,n,$$

where  $c_{s,i}$   $(i=0,\ldots,s)$  are barycentric coordinates of  $y_s$ . Now, it is sufficient to note that  $b_{\alpha_0,\ldots,\alpha_{s-1},\gamma}=a_{\alpha_0,\ldots,\alpha_{s-1},0}^{\gamma}$   $(\gamma=0,\ldots,r)$ . Since  $r\leq n$ , the algorithm (20) can be expressed as:

(21) 
$$a_{\alpha_0,\dots,\alpha_s}^0 = a_{\alpha_0,\dots,\alpha_s},$$
$$a_{\alpha_0,\dots,\alpha_s}^{\gamma} = \sum_{i=0}^s c_{s,i} E_i a_{\alpha_0,\dots,\alpha_s}^{\gamma-1}, \quad \text{for } \gamma = 1,\dots,r,$$

where  $c_{s,i}$  (i = 0, ..., s) are barycentric coordinates of  $y_s$ .

Discussion of the algorithm for evaluation of the coefficients in general case will be given in other paper.

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